

AD-A065 418 NAVY UNDERWATER SOUND LAB NEW LONDON CONN F/G 20/1  
CONTINUOUS GRADIENT RAY TRACING SYSTEM (CONGRATE) BOTTOM LOSS M--ETC(U)  
FEB 70 J S COHEN, T A GARRETT  
UNCLASSIFIED USL-TM-2070-35-70 NL

UNCLASSIFIED

F/G 20/1  
SS M--ETC(U)

USL-TM-2070-35-70

NL

Size	10
Age	10
Weight	10

END  
DATE  
FILMED  
4-79  
DDC

DDC

# LEVEL

(1)

Code \_\_\_\_\_

Copy 1/100

USL Problem No.  
A-001-11-00

ADA065418

Navy Underwater Sound Laboratory  
New London, Connecticut 06320

6  
CONTINUOUS GRADIENT RAY TRACING SYSTEM  
(CONGRATS) BOTTOM LOSS MODELS.

by

10  
Jeffrey S./Cohen and Thelda A./Garrett

9  
USL Technical Memorandum No. 2070-35-70

11  
5 February 1970

14  
USL-TM-2070-35-70

DDC  
RECEIVED  
MAR 8 1979  
C

12  
44p.

## INTRODUCTION

CONGRATS (CONTinuous Gradient Ray Tracing System) is an integrated collection of ray tracing programs designed to construct ray diagrams, to determine multipath eigenrays, to model acoustic propagation, to compute boundary and volume reverberation, and to solve numerous additional problems in underwater acoustics. The CONGRATS series has been documented in references (a), (b), and (c).

Bottom reflection loss is often an important factor in acoustic field predictions. The foundational CONGRATS programs, S0990 and S0991, require an input table of bottom loss in decibels as a function of grazing angle in degrees. This data is often difficult to obtain directly. Hence, various expressions have been developed to model bottom loss versus grazing angle.

If a predetermined table is not supplied, bottom loss values may be computed automatically by one of four models which have been added to the CONGRATS programs, S0990 and S0991. The first model, which depends on source frequency, is a least-squares fit of a fourth degree polynomial surface to modified AMOS bottom loss data. The model was developed by Dr. E. S. Eby (see reference (d)). The second model, supplied to the authors by E. M. Podeszwa, is an approximation to average bottom losses in MGS Acoustic Provinces 1, 2, 3, 4, and 5. The third and fourth models are empirical bottom reflection loss expressions, depending on both source frequency and bottom porosity, developed by NEL (described in reference (e)) and NUWC (see reference (f)), respectively. This memorandum will describe the four models, make simple comparisons, describe the input options needed to use the various

Approved for public release; distribution unlimited.

254 200

79 02 28 164 LB

DDC FILE COPY

models, and provide a listing of the revised Subroutines INPUT and BLOSS and the new Subroutine BTMLOS.

## DISCUSSION OF MODELS

### BOTTOM LOSS TABLES

When an acoustic ray reflects from the ocean bottom, the intensity of the ray diminishes. The amount of power lost depends on the frequency of the ray, the angle with which the ray intersects the bottom, and the characteristics of the bottom. If the bottom characteristics are assumed to be constant over the area of interest and if the frequency of each ray is assumed to be the source frequency, the bottom loss depends on grazing angle alone. In order to calculate bottom loss for each ray, the CONGRATS programs require a table of bottom loss values for grazing angles varying from  $0^\circ$  to  $90^\circ$  in increments of  $1^\circ$ . Linear interpolations are performed between these values in order to compute bottom loss for other grazing angles. This table may be supplied by the user on eleven computer cards. The first card contains the words "BOTTOM" and "LOSS" starting in columns 1 and 11, respectively (see Fig. 1(a)). Ten cards containing the 91 necessary values of bottom loss in decibels must follow the BOTTOM LOSS card (see reference (a)). The use of this table allows the bottom loss curve to be completely arbitrary.

### AMOS BOTTOM LOSS

If the user is not familiar with the bottom characteristics but does know the frequency at which he is operating, the bottom loss table can be generated by the least-squares fit to modified AMOS data described in reference (d). This fit is good only for grazing angles less than  $60^\circ$ , however. Hence, an approximation to bottom loss data (presented in reference (d)) was developed by the authors for grazing angles steeper than  $60^\circ$ . The combination of this high-angle approximation and the least-squares fit was programmed for the CONGRATS series. The equations used are shown in Table 1. In order to implement the use of this model, the card shown in Fig. 1(b) must be used instead of the BOTTOM LOSS set described in reference (a). It should be noted that a FREQUENCY card (see reference (a)), such as the one in Fig. 2, must precede this BOTTOM LOSS card. Figure 3 is a graph of the approximated AMOS bottom loss versus grazing angle for frequencies of 250, 500, 1000, 2000, and 4000 Hz. The general trend shown in the plot is that bottom loss increases with frequency.

SECTION for	White Section <input checked="" type="checkbox"/>	Buff Section <input type="checkbox"/>
ITIS		
DOC		
UNANNOUNCED		
JUSTIFICATION		
BY	DISTRIBUTION/AVAILABILITY CODES	
	SPECIAL	
A		

79 02 28 164



#### MGS BOTTOM LOSS

If the bottom losses in the operational area of interest are known to be similar to those of one of the MGS Acoustic Provinces, an approximation to the average bottom losses in Province 1, 2, 3, 4, or 5 can be supplied by the CONGRATS programs. The mathematical expressions used as the approximations are shown in Table 2. These formulas depend only on grazing angle, so bottom loss tables can be supplied by the programs with no additional data. The approximate bottom losses of MGS Acoustic Province 1, 2, 3, 4, or 5 will be computed if the BOTTOM LOSS card shown in Fig. 1(c), (d), (e), (f), or (g), respectively, appears in the data deck. The bottom losses of the five MGS Acoustic Provinces are plotted in Fig. 4. For typical sonars in use today, Provinces 1 and 2 provide excellent to good bottom reflectivity, Province 3 provides a fair bottom bounce area, and Provinces 4 and 5 are marginal to unusable.

#### NEL BOTTOM LOSS

The composition of the bottom, which can be usefully classified by the single parameter porosity, is an important factor in determining bottom reflectivity. Table 3 (reproduced from reference (f)) presents porosity as a function of bottom composition, with the bottom varying from fine clay (high bottom loss) to very coarse sand (high bottom reflectivity). The bottom loss model developed by the Naval Electronics Laboratory (and described in reference (e)) depends on both source frequency and bottom porosity, as well as grazing angle. The equation used is presented in Table 4. Figure 5 is a plot of NEL bottom loss versus grazing angle for frequencies of 250, 500, 1000, 2000, and 4000 Hz and a constant porosity of 0.60. The bottom loss increases with frequency in a fashion similar to that shown in the AMOS approximation. Figure 6 is a plot of NEL bottom loss versus grazing angle for porosities varying from 0.30 to 0.90 in steps of 0.15 and a constant frequency of 1 kHz. As bottom porosity increases, bottom loss also increases. Figure 1(h) presents the data card required to cause the NEL bottom loss equation to be used by the CONGRATS series for a porosity of 0.60 and a previously determined frequency.

#### NUWC BOTTOM LOSS

The Naval Undersea Warfare Center has developed a newer bottom loss expression, based primarily on the AMOS results, which also depends on both source frequency and bottom porosity (see reference (f)). The equation is presented in Table 4, below the equation used by NEL. The frequency factor, ABTMLOS, is a function consisting of straight line segments joining eight specified points. The eight points are tabulated in Fig. 7 and a plot of the function is drawn. The NUWC bottom



loss increases with frequency and porosity (shown in Figs. 8 and 9, respectively) as did the NEL bottom loss. If the card shown in Fig 1(i) appears in the data deck, the NUWC bottom loss model is used by the CONGRATS programs for a porosity of 0.40 and a previously inputted frequency.

#### COMPARISON

For a frequency of 3.5 kHz the bottom loss curves derived from the AMOS, NEL, and NUWC models (with a porosity of 0.40 used in the NEL and NUWC approximations) are plotted in Fig. 10. If source frequency is the only information available, the AMOS model produces a reasonable approximation to a characteristic bottom loss curve. If a small (large) bottom porosity (and hence high (low) bottom reflectivity) is used in the NEL or NUWC equations, the bottom loss curve produced, at any given frequency, is lower (higher) than the curve produced by the AMOS approximation, which was developed for an average bottom. This phenomenon is demonstrated for a low porosity in Fig. 10. For a given frequency and porosity, the NEL model usually gives higher bottom loss curves than the NUWC model, especially for smaller grazing angles. The general shape and relationship of the two curves is shown in Fig. 10. If no other criterion is available for choosing between the NEL and NUWC bottom loss expressions, it should be noted that the NUWC model was developed more recently and is more widely accepted. If the operating area has been previously classified as an IGS Acoustic Province, the CONGRATS approximations to the average bottom losses in Provinces 1 - 5 can be considered quite reliable.

#### DISCUSSION OF INPUT

The choice of bottom loss model depends on the units field (the ten-column alphanumeric field starting in column 21 -- see reference (a)) of the BOTTOM LOSS card appearing in the CONGRATS data deck. A list of the nine words that may be used in the units field, a brief description of the model implemented by each, and a reference to a sample card are shown in Table 5. If the AMOS, NEL, or NUWC model is used, a FREQUENCY card (see reference (a)), such as the one shown in Fig. 2, must precede the BOTTOM LOSS card. The ten-column numeric field starting in column 31 of the BOTTOM LOSS card contains the porosity of the bottom if the NEL or NUWC expressions are used.

An option has been provided to input a minimum and/or maximum bottom loss value in decibels to be accepted by the CONGRATS programs. A bottom loss value calculated to be smaller (larger) than the minimum (maximum) bottom loss is converted to the minimum (maximum) value. The ten-column numeric fields starting in columns 41 and 51 of the BOTTOM LOSS card contain the minimum and maximum, respectively. If these

fields are left blank a minimum of 0 dB and a maximum of 500 dB will be assumed. This option cannot be used if a bottom loss table is inputted.

#### SUMMARY

The fundamental CONGRATS programs, S0990 and S0991, have been revised to calculate bottom loss as a function of grazing angle. The bottom loss curves have been computed with frequency, MGS Acoustic Province, and both frequency and porosity as basic parameters. The bottom loss models have been described in detail, examples and comparisons have been provided, and the new input options have been explained. Subroutines INPUT and BLOSS have been revised in order to accommodate the new bottom loss models, and a new subroutine, Subroutine BTMLOS, has been written to compute the bottom loss curves. These three routines are listed in the appendix. The ray plotting, eigenray generation, and eigenray processing functions of the CONGRATS series have not been altered in any way other than as described in this memorandum. It is hoped that the additional bottom loss options will be a convenience for users of the CONGRATS series.

*Jeffrey S. Cohen*

JEFFREY S. COHEN  
Mathematician

*Thelda A. Garrett*

THELDA A. GARRETT  
Math Aid

#### REFERENCES

- (a) H. Weinberg, "CONGRATS I: Ray Plotting and Eigenray Generation," USL Report No. 1052, 30 October 1969.
- (b) J. S. Cohen and L. T. Einstein, "CONGRATS II: Eigenray Processing Programs," USL Report No. 1069, 5 February 1970.
- (c) J. S. Cohen and T. A. Garrett, "CONGRATS Temperature and Salinity Sound Speed Conversion," USL Technical Memorandum No. 2070-412-69, 10 November 1969.

- (d) E. S. Eby and B. W. Perneski, "Least-Squares Fit To Bottom Loss As A Function Of Frequency And Grazing Angle," USL Technical Memorandum Ser. No. 921-055-62, 25 September 1962.
- (e) Sonar Simulation Computer Programs Phase I Interim Technical Report, Vol. 1, Contract N00140-68-C-0372, 21 November 1968, General Electric Company, Heavy Military Electronics Systems, Syracuse, New York.
- (f) H. R. Hall and W. H. Watson, "An Empirical Bottom Reflection Loss Expression For Use In Sonar Range Prediction," July 1967, Naval Undersea Warfare Center, San Diego, California.



TABLE 1  
AMOS Equations

Let  $f$  = frequency(kHz),  $\theta$  = Grazing Angle(deg),  $N_B$  = Bottom Loss(dB)

If  $f \leq 1$  kHz,

for  $\theta = 0^\circ$ :  $N_B = 0.0$

for  $1^\circ \leq \theta \leq 14^\circ$ :  $N_B = 2.96026 + 1.26990F + 1.60430\phi + .25257F^2$   
 $+ .66161F\phi + .06072\phi^2 + .02000F^3 + .09833F^2\phi$   
 $- .01888F\phi^2 - .02619\phi^3 - .00303F^4 + .00778F^3\phi$   
 $- .00833F^2\phi^2 - .01250F\phi^3 - .01310\phi^4$   
 where  $\phi = (\theta - 10)/5$  and  $F = \log_2 f$

for  $15^\circ \leq \theta \leq 39^\circ$ :  $N_B = 4.35024 + 1.17091F + .46874\phi + .08272F^2$   
 $+ .17115F\phi - .07547\phi^2 - .00386F^3 + .01295F^2\phi$   
 $- .01678F\phi^2 - .00555\phi^3 - .00003F^4 - .00193F^3\phi$   
 $- .00074F^2\phi^2 - .00224F\phi^3 + 0.0\phi^4$   
 where  $\phi = (\theta - 30)/5$  and  $F = 2 \log_2 f + 3$

for  $40^\circ \leq \theta \leq 60^\circ$ :  $N_B = 4.84820 + 1.46858F - .11457\phi + .11036F^2$   
 $- .01238F\phi - .00953\phi^2 - .01000F^3 - .00375F^2\phi$   
 $- .00929F\phi^2 + .00833\phi^3 + 0.0F^4 - .00042F^3\phi$   
 $- .00268F^2\phi^2 + .00830F\phi^3 - .00208\phi^4$   
 where  $\phi = (\theta - 50)/5$  and  $F = 2 \log_2 f + 3$

for  $61^\circ \leq \theta \leq 90^\circ$ :  $N_B = 4.61430 + 1.47306F - .04751\phi + .09214F^2$   
 $- .01084F^3 - .01271F\phi$   
 where  $\phi = \theta - 60$  and  $F = 2 \log_2 f + 3$

NOTE: For  $61^\circ \leq \theta \leq 90^\circ$   $N_B$  can also be written:  
 $N_B = N_B(\theta - 1) - .085667 - .025434F$   
 where  $F = \log_2 f$

TABLE 1 (Continued)  
AMOS Equations

If  $f > 1$  kHz,

for  $\theta = 0^\circ$ :  $N_B = 0.0$

for  $1^\circ \leq \theta \leq 14^\circ$ :  $N_B = 2.96026 + 1.26990F + 1.60430\phi + .25257F^2$   
 $+ .66161F\phi + .06072\phi^2 + .02000F^3 + .09833F^2\phi$   
 $- .01888F\phi^2 - .02619\phi^3 - .00303F^4 + .00778F^3\phi$   
 $- .00833F^2\phi^2 - .01250F\phi^3 - .02310\phi^4$   
 where  $\phi = (\theta - 10)/5$  and  $F = \log_2 f$

for  $15^\circ \leq \theta \leq 39^\circ$ :  $N_B = 12.25083 + 3.88808F + 1.14802\phi + .16312F^2$   
 $+ .04386F\phi - .18835\phi^2 - .02857F^3 - .08214F^2\phi$   
 $- .05952F\phi^2 + .00667\phi^3 + .01071F^4 - .00179F^3\phi$   
 $+ .00476F^2\phi^2 + .01389F\phi^3 - .00348\phi^4$   
 where  $\phi = (\theta - 30)/5$  and  $F = \log_2 f - 1$

for  $40^\circ \leq \theta \leq 60^\circ$ :  $N_B = 13.59067 + 3.74190F - .25928\phi + .13266F^2$   
 $- .03764F\phi - .08816\phi^2 - .01333F^3 + .01214F^2\phi$   
 $- .00959F\phi^2 + .00500\phi^3 - .02000F^4 - .00167F^3\phi$   
 $+ .00867F^2\phi^2 - .00167F\phi^3 + .00083\phi^4$   
 where  $\phi = (\theta - 50)/5$  and  $F = \log_2 f - 1$

for  $61^\circ \leq \theta \leq 90^\circ$ :  $N_B = 12.77275 + 3.61490F - .126335\phi + .19162F^2$   
 $- .000333F\phi - .01667F^3 + .034002\phi/(F + 1)$   
 $- .02000F^4$   
 where  $\phi = \theta - 60$  and  $F = \log_2 f - 1$

NOTE: For  $61^\circ \leq \theta \leq 90^\circ$   $N_B$  can also be written:  
 $N_B = N_B(\theta - 1) - .126002 - .000333F + .034002/F$   
 where  $F = \log_2 f$

TABLE 2  
MGS Equations

Let  $\theta$  = Grazing Angle(deg) and  $N_B$  = Bottom Loss(dB)

for Province 1:

$$N_B = 2.2435 \log_e(.1260\theta + 1.496)$$

for Province 2:

$$N_B = 3.4315 \log_e(.1056\theta + 2.842)$$

for Province 3:

$$N_B = 2.4910 \log_e(.8864\theta + 10.526)$$

for Province 4:

$$N_B = 2.8377 \log_e(1.8754\theta + 15.685)$$

for Province 5:

$$N_B = 2.4036 \log_e(20.5760\theta + 82.440)$$



TABLE 3  
Porosity

Bottom Composition	Approximate Porosity	
Fine clay	0.93	(High Loss)
Medium clay	0.87	
Coarse clay	0.81	
Very fine silt	0.75	
Fine silt	0.69	
Medium silt	0.63	
Coarse silt	0.57	
Very fine sand	0.51	
Fine sand	0.45	
Medium sand	0.39	
Coarse sand	0.33	
Very coarse sand	0.27	(Low Loss)

TABLE 4  
NEL and NUWC Equations

NEL Equation:

$$N_B = \left[ 6 + 22(P - .27) + 10 \log_{10} f \right] \cdot \left[ \text{TANH}((P/.24) \cdot (\theta/57.296)) + ((1 - P/.24)/12.5) \cdot (\theta/90)^2 \right]$$

NUWC Equation:

$$N_B = \left[ 3.7 + 17.5(P - .27) \right] \cdot \left[ \text{ABTMLOS}(f) \right] \cdot \left[ \text{TANH}((P/.24) \cdot (\theta/57.296))^{1.5/P} + ((1 - P/.27)/12.5) \cdot (\theta/90)^2 \right]$$

where:  $N_B$  = Bottom Loss(dB)  
 $f$  = Frequency(kHz)  
 $P$  = Porosity  
 $\theta$  = Grazing Angle(deg)

NOTE: ABTMLOS is a function of frequency defined in Figure 7.

**TABLE 5**  
**Bottom Loss Model Options**

Units Word	Sample Card	Model
	Fig. 1(a)	Inputted Table of Values.
AMOS	Fig. 1(b)	Least-Squares Fit to Modified AMOS data.
MGS1	Fig. 1(c)	Average Bottom Losses in MGS Acoustic Province 1.
MGS2	Fig. 1(d)	Average Bottom Losses in MGS Acoustic Province 2.
MGS3	Fig. 1(e)	Average Bottom Losses in MGS Acoustic Province 3.
MGS4	Fig. 1(f)	Average Bottom Losses in MGS Acoustic Province 4.
MGS5	Fig. 1(g)	Average Bottom Losses in MGS Acoustic Province 5.
NEL	Fig. 1(h)	Empirical Expression (NEL).
NUWC	Fig. 1(i)	Empirical Expression (NUWC).



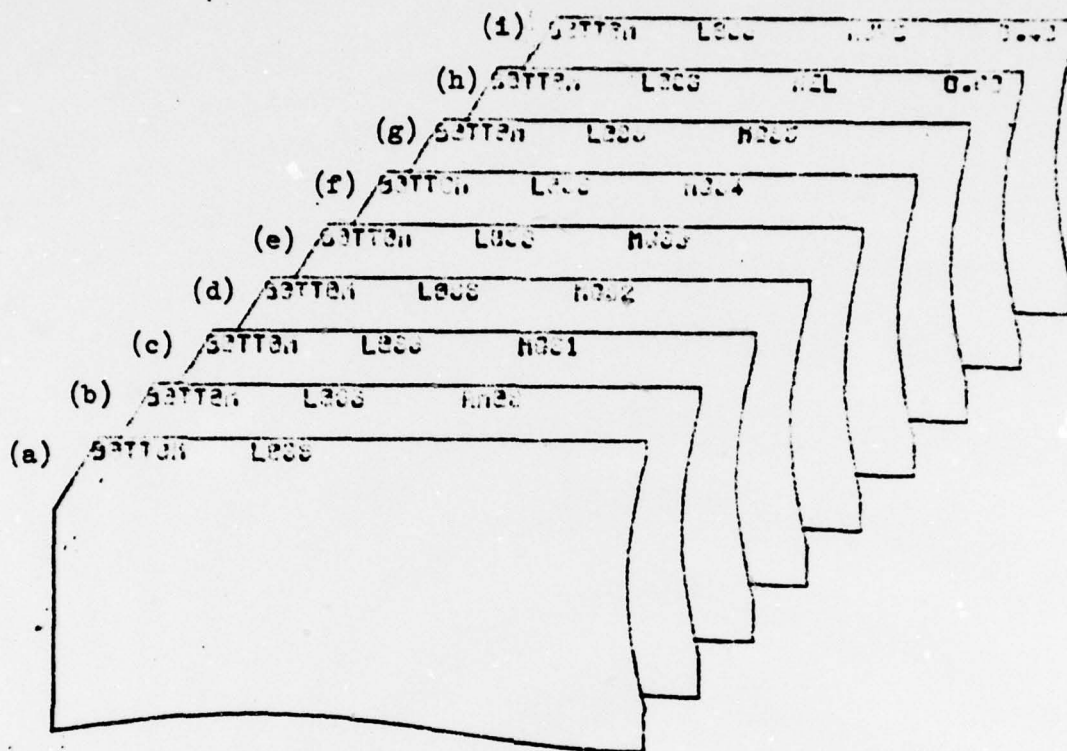


Fig. 1 - BOTTOM LOSS Cards

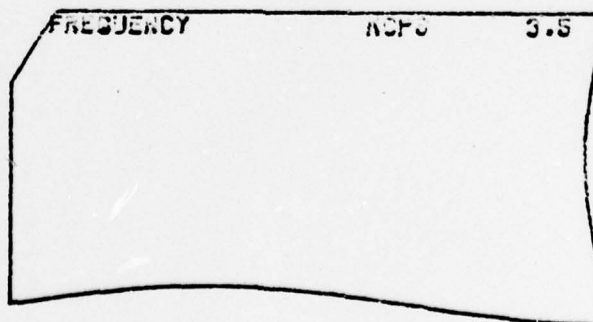


Fig. 2 - FREQUENCY Card

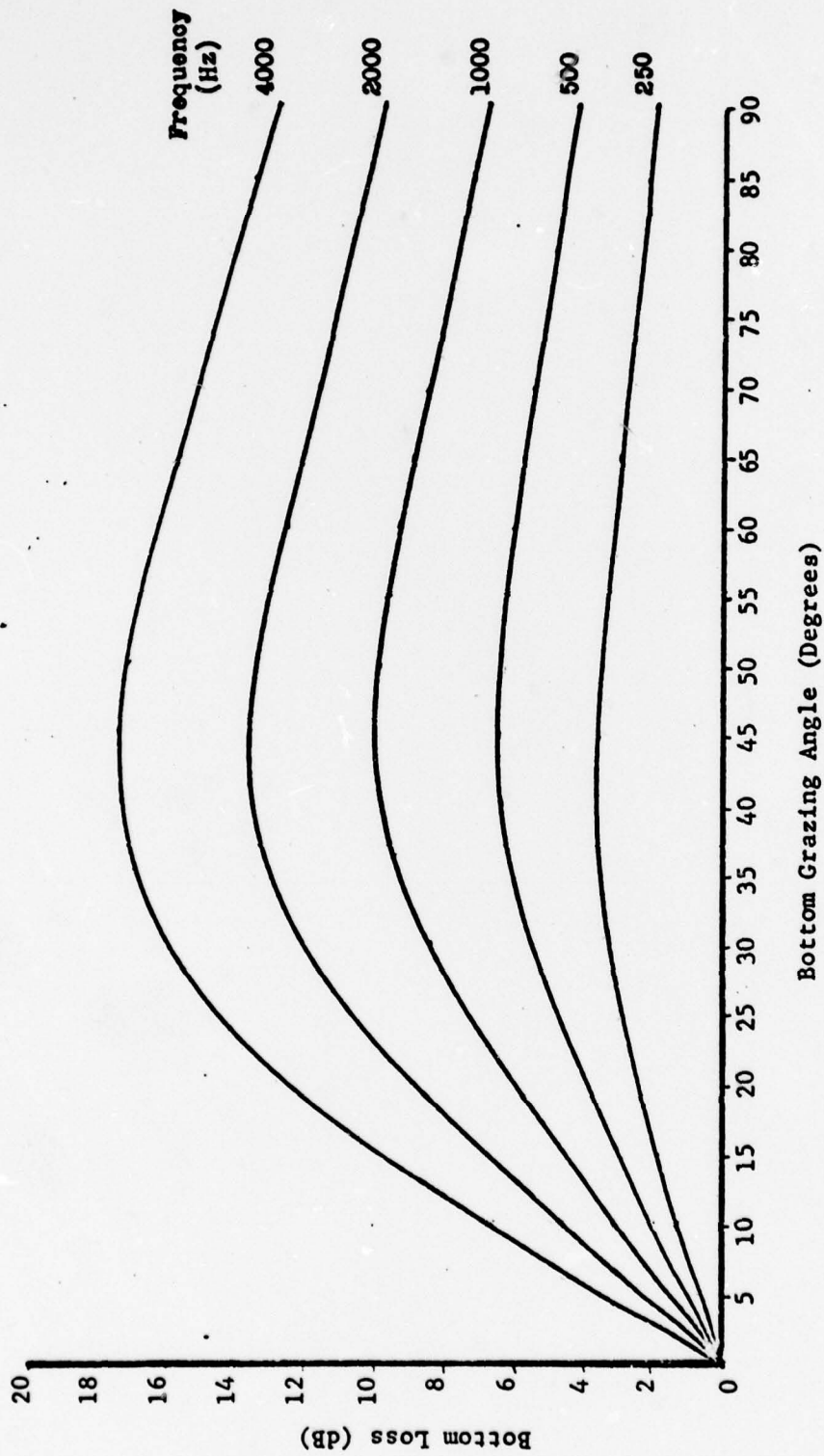


Fig. 3 - AMOS Bottom Loss Curves

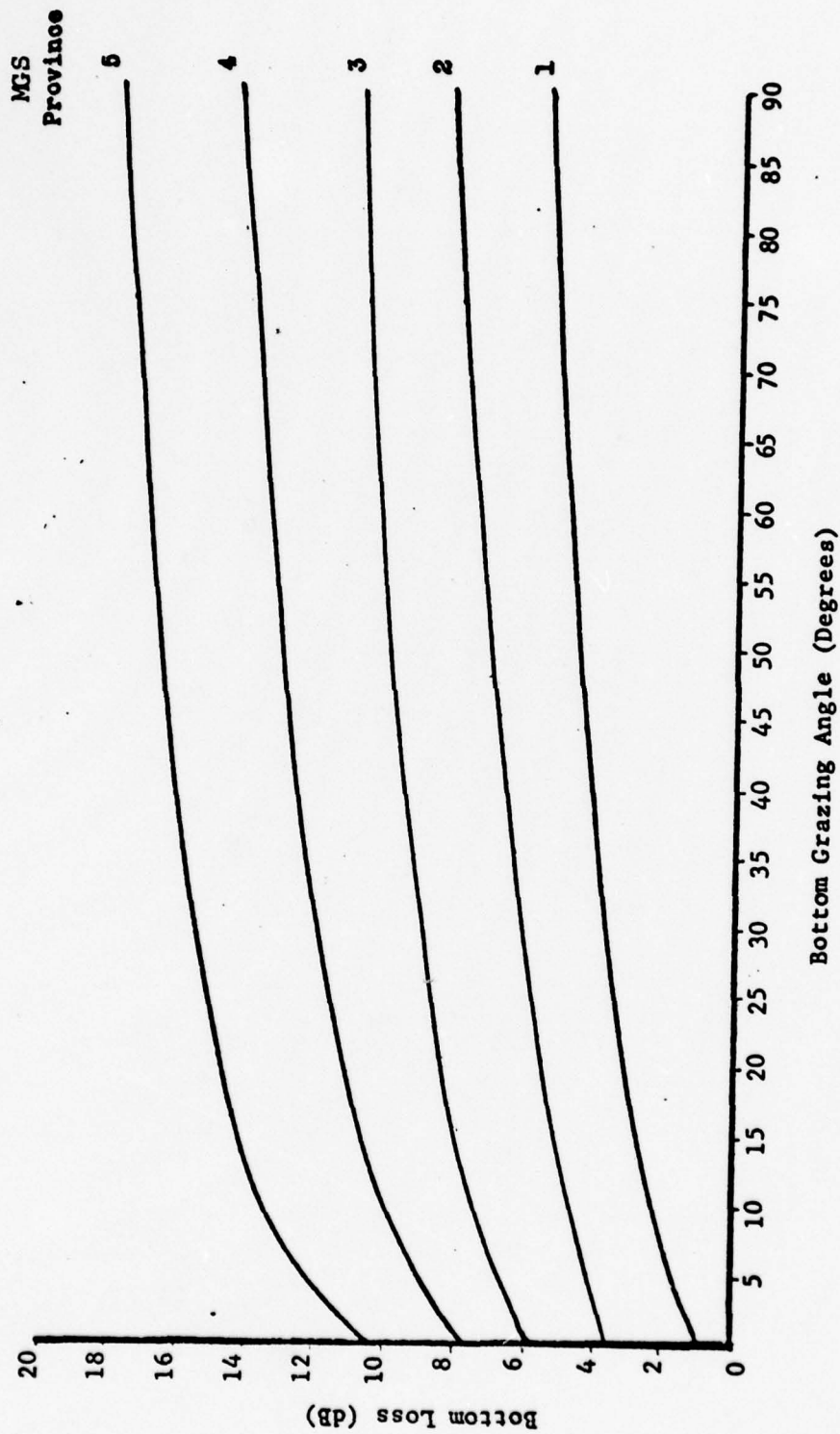


Fig. 4 - MGs Bottom Loss Curves

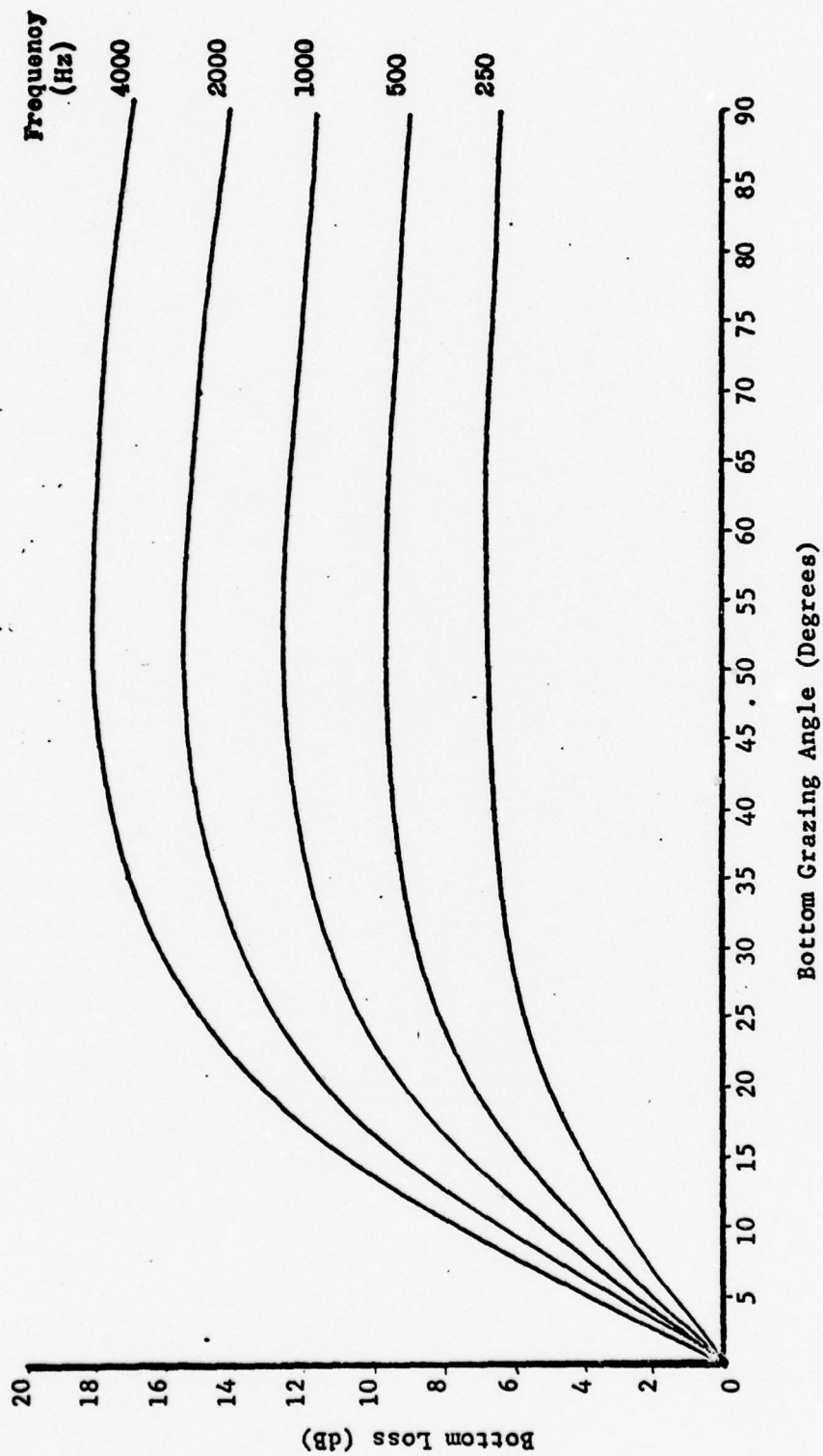


Fig. 5 - NEL Bottom Loss Curves  
(Porosity = 0.60)



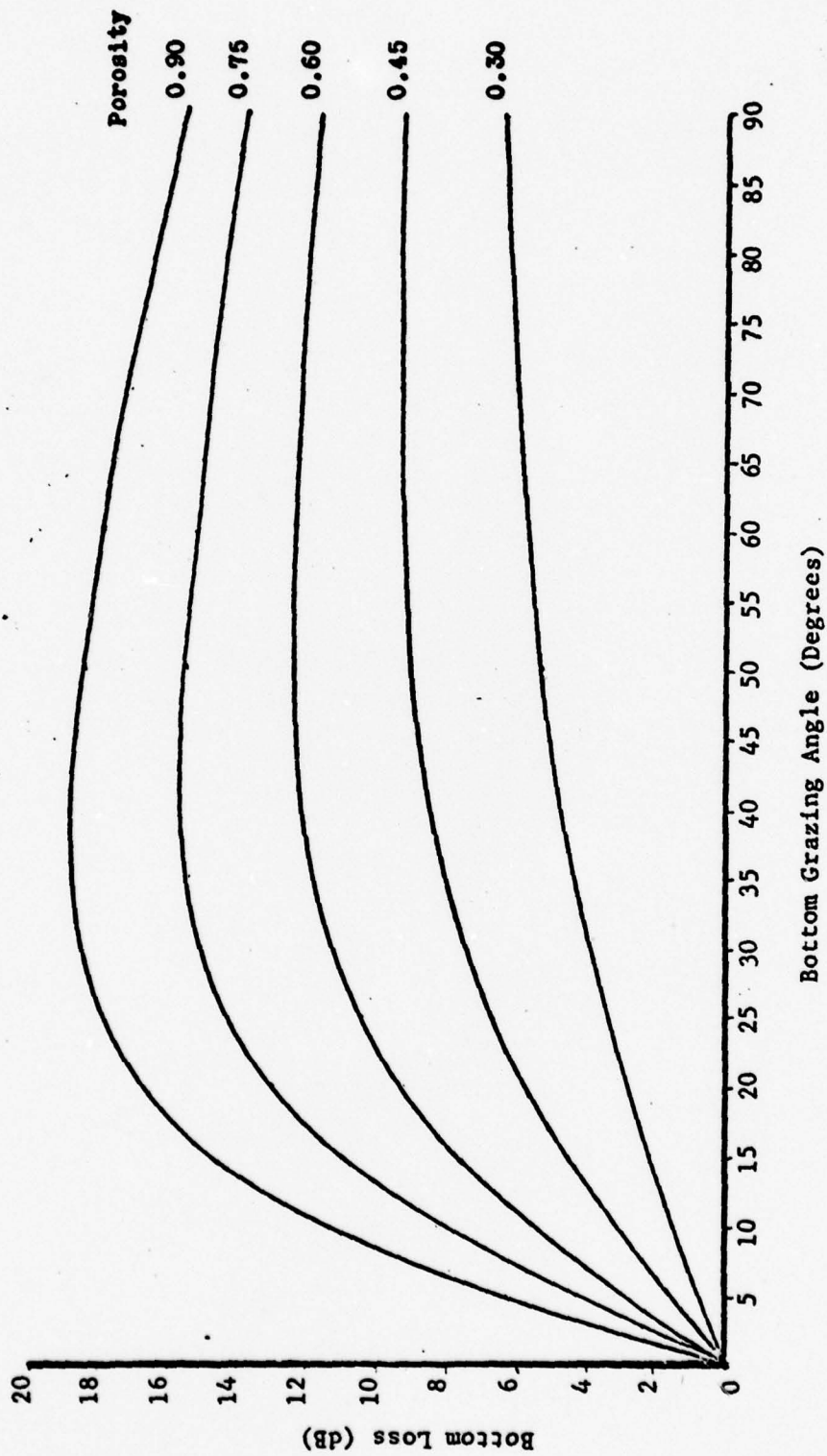


Fig. 6 - NEL Bottom Loss Curves  
(Frequency = 1 kHz)

TABULATED FUNCTION  
ABTMLOS

FREQUENCY	VALUE
.1	.157
.3	.45
.5	.67
1	1
1.5	1.18
2.5	1.43
4	1.70
6.5	2

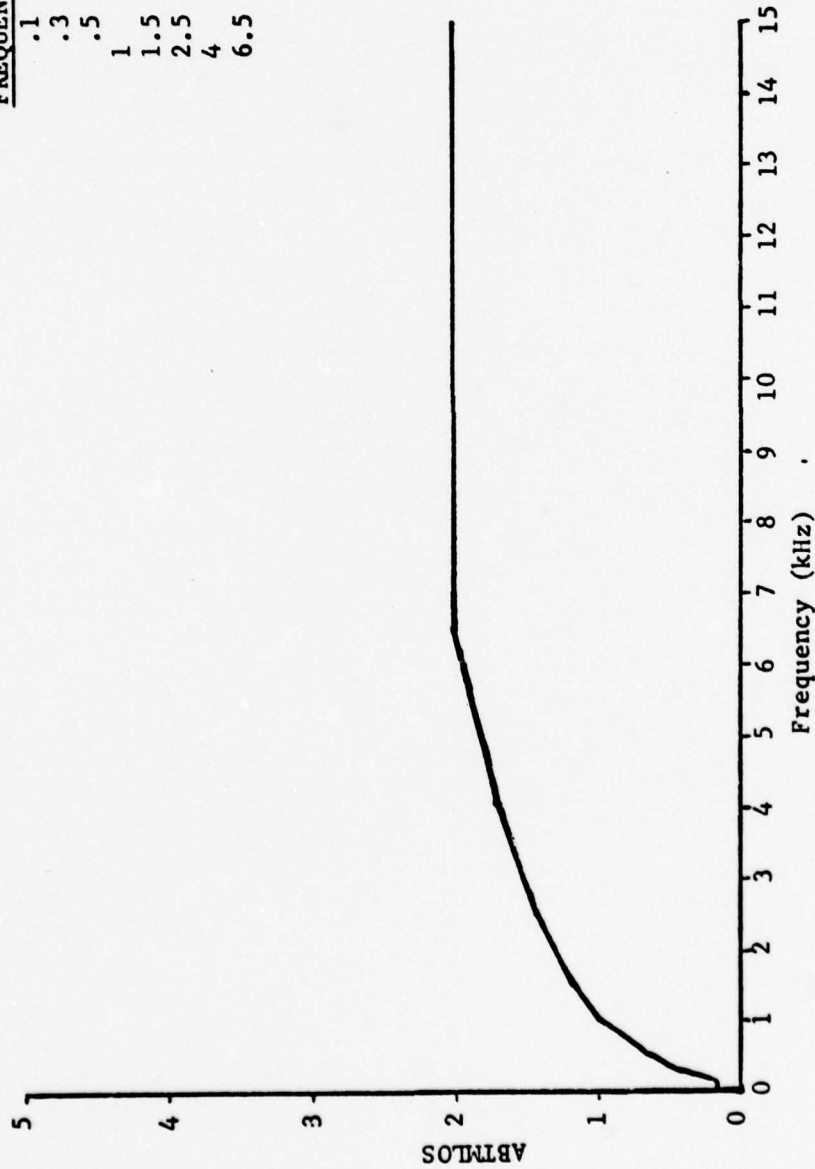


Fig. 7 - Function ABTMLOS

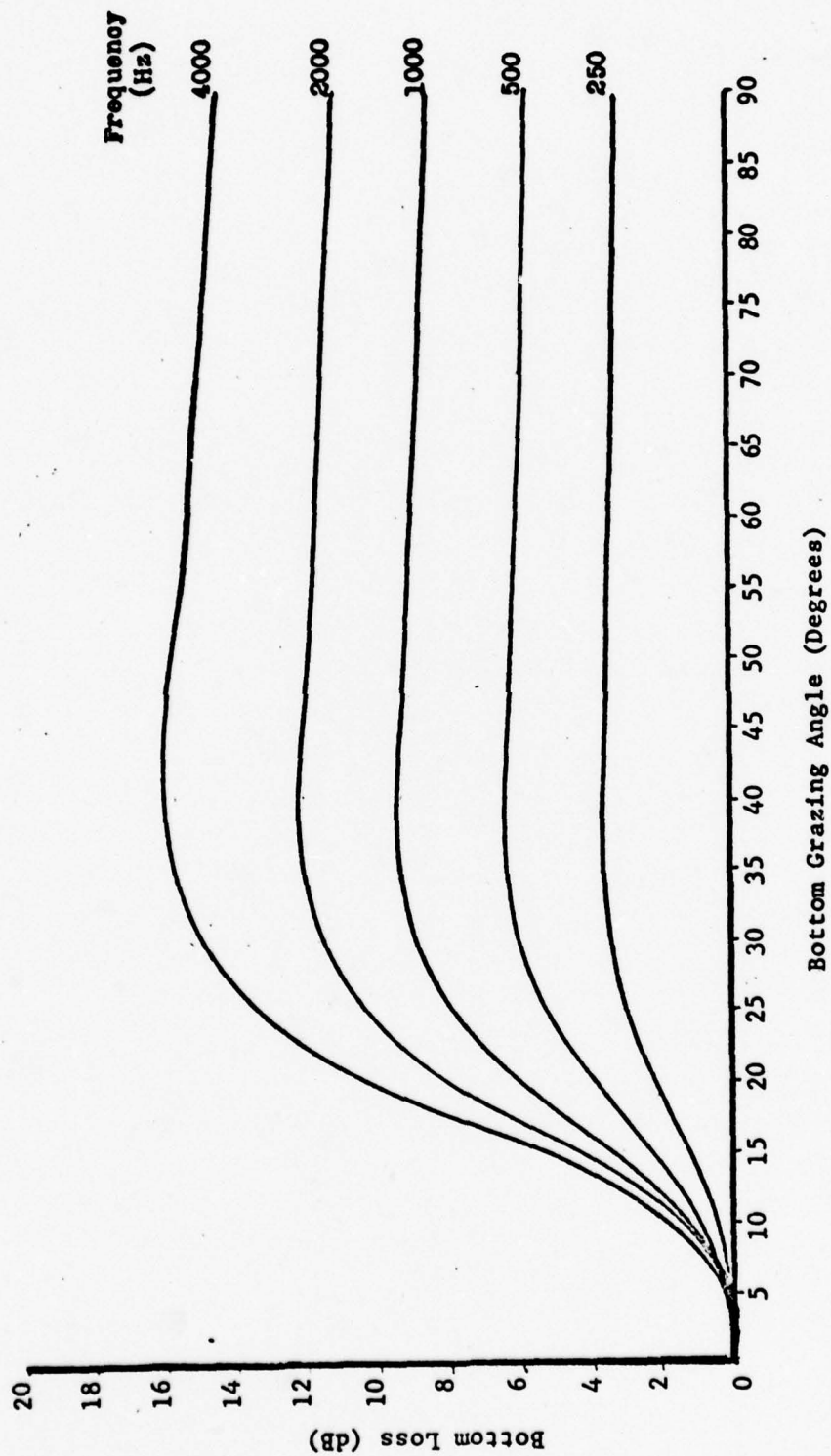


Fig. 8 - NUWC Bottom Loss Curves  
(Porosity = 0.60)

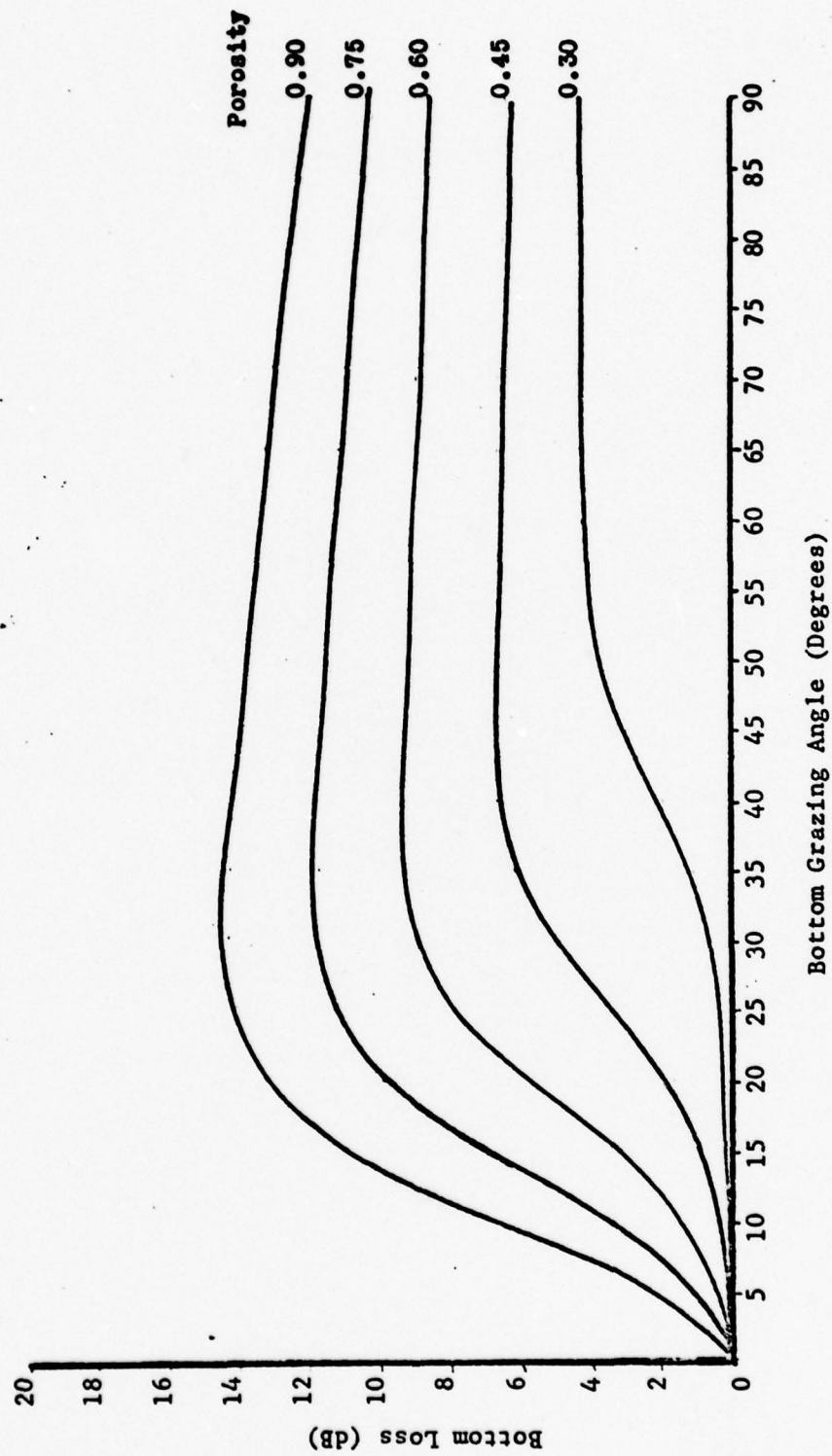


Fig. 9 - NUWC Bottom Loss Curves  
(Frequency = 1 kHz)



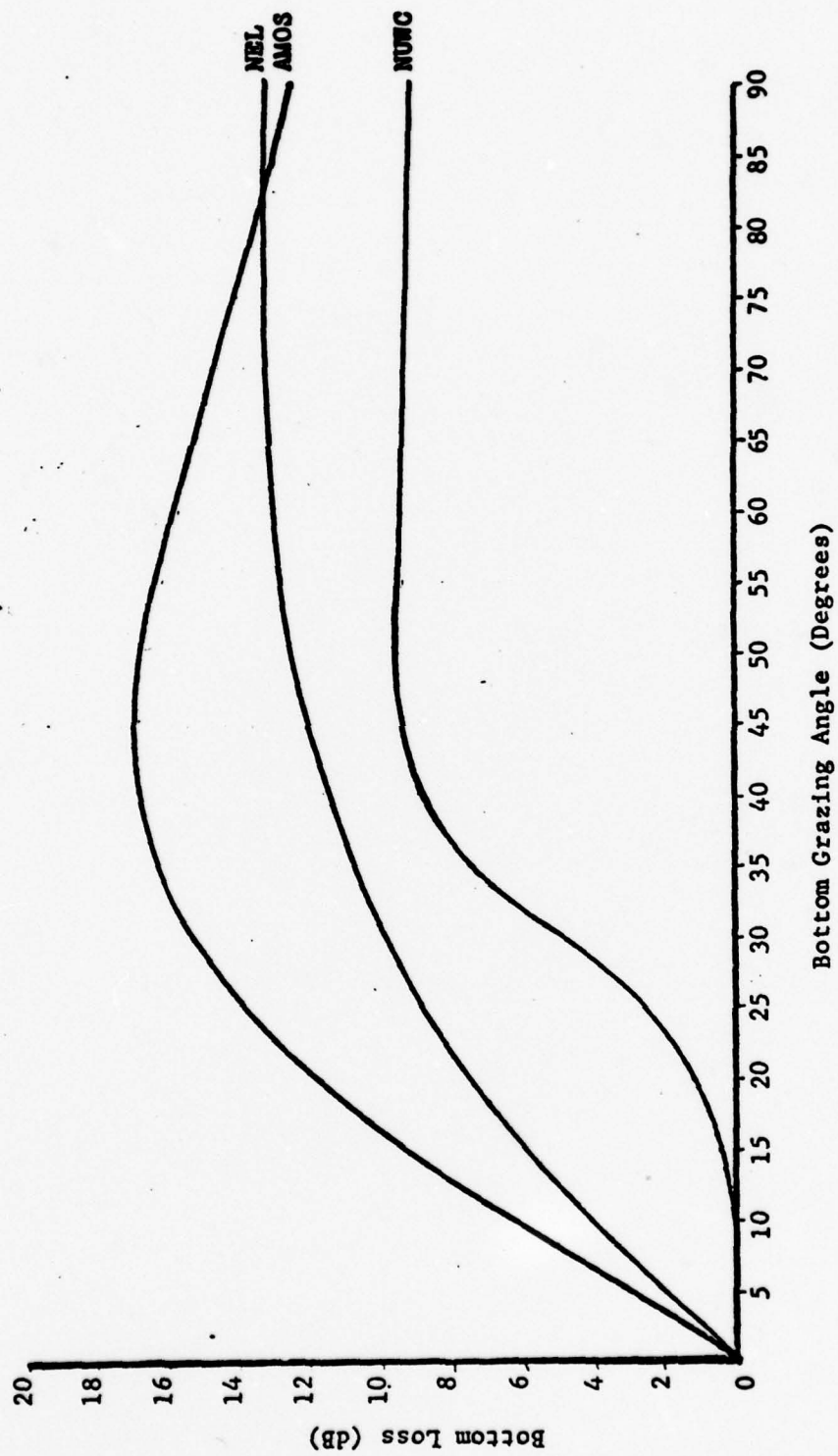


Fig. 10 - AMOS, NEL, NUWC Bottom Loss Curves  
(Frequency = 3.5 kHz, Porosity = 0.40)

APPENDIX  
Subroutine Listings

USL Tech Memo  
No. 2070-35-70

SUBROUTINE INPUT FOR CONGRATS.

CHIC WEINBERG

SUBROUTINE INPUT

```

DIMENSION TARGET(1010,3),ANGLES(1010),SONAR(5,2),SURFAC(5),
1 SP(210,2),BOTTOM(5),BP(210,2),TOLERA(5),VP(210,2),TP(210,3)
DIMENSION GROUP(11)/66HCOMMENTARGETSONAR SURFACBOTTOMVELOCITHERMA
1PROCESND FREQUEMAXIMU/
DIMENSION COORD(8)/48HRANGE DEPTH ANGLE LOSS TOLERAAXES PROFILP
1HASE /
DIMENSION UNITS(2,32)/
1 1.09361111E-5, 6HCM , 1.09361111E-5, 6HCM/S ,
2 2.77777777E-5, 6HIN , 2.77777777E-5, 6HIN/S ,
3 0.33333333E-3, 6HFT , 0.33333333E-3, 6HFT/S ,
4 1.00000000E-3, 6HYD , 1.00000000E-3, 6HYD/S ,
5 1.09361111E-3, 6HM , 1.09361111E-3, 6HM/S ,
6 2.00000000E-3, 6HF , 2.00000000E-3, 6HF/S ,
7 0.33333333E-0, 6HKFT , 0.33333333E-0, 6HKFT/S ,
8 1.00000000E-0, 6HKYD , 1.00000000E-0, 6HKYD/S ,
9 1.09361111E-0, 6HKM , 1.09361111E-0, 6HKM/S ,
T 1.76000000E-0, 6HMI , 1.76000000E-0, 6HMI/S ,
1 2.02680000E-0, 6HNM MI , 2.02680000E-0, 6HKNOTS ,
2 1.74532925E-2, 6HDEG , 1.74532925E-2, 6HDEG/S ,
3 1.00000000E-0, 6HRAD , 1.00000000E-0, 6HRAD/S ,
4 6.28318531E-0, 6HCPS , 6.28318531E+3, 6HKCPS ,
5 1.00000000E-3, 6HMS , 1.00000000E-0, 6HSEC ,
6 1.00000000E-0, 6HC , 5.55555555E-1, 6HFAHR /
DIMENSION TEST(12),FMT(12),DATA(2048),REVMAX(4)
DIMENSION CMMNT(12)/72H THERE SHOULD BE AT LEAST ONE COMMENT SET
1.
DATA PRINT/6HPRINT /,LINMAX/60/,ICMMNT/0/
COMMON TARGET,ANGLES,SONAR,SURFAC,SP,BOTTOM,BP,TOLERA,VP,
1 REVMAX,PROCES

```

SET INITIAL CONDITIONS.

```

-----
ANGLES(1010) = 0.0
TARGET(1010,1) = 0.0
TARGET(1010,2) = 0.0
IHEAD = 0
LINES = LINMAX
NPRINT = FLD(33,3,PROCES)
NTAPE1 = FLD(30,3,PROCES)
NTAPE2 = FLD(27,3,PROCES)

```

CHECK THE GROUP CODE.

```

-----
100 READ 101, (TEST(J),J=1,9)
101 FORMAT( 3(A6,A4), 3F10,5 )
DO 110 I=1,11
IF( TEST(1).GT.GROUP(I) .OR. TEST(1).LT.GROUP(I) ) GO TO 110
IGROUP = I

```

```

110 GO TO (1000,200,200,200,200,200,200,8000,9000,300,9200), IGROUP
C
C 110 CONTINUE
C
C THE GROUP CODE IS INCORRECT.
120 FMT(1) = (+6HGROUP )
130 PRINT 132, FMT(1)
132 FORMAT( 10X 14HTHE FOLLOWING , A6, 18HCODE IS INCORRECT. )
140 PRINT 142, ( TEST(J),J=1,9 )
142 FORMAT( 24X 6A6, 3F12.5 )
150 PRINT 152
152 FORMAT( 10X 28HTHE PROGRAM CANNOT CONTINUE. )
STOP 6

C
C
C CHECK THE COORD CODE.
C -----
200 DO 210 I=1,8
IF( TEST(3).GT.COORD(I) .OR. TEST(3).LT.COORD(I) ) GO TO 210
ICoord = I
GO TO (300,300,300,500,300,300,600,500), ICoord
210 CONTINUE

C
C THE COORD CODE IS INCORRECT.
C FMT(1) = (+6HCOORD )
C GO TO 130

C
C
C CHECK THE UNITS CODE.
C -----
300 DO 310 I=1,30
IF( TEST(5).GT.UNITS(2,I) .OR. TEST(5).LT.UNITS(2,I) ) GO TO 310
Iunits = I
IF( IGROUP.EQ.10 ) GO TO 320
IF( ICoord.GE.6 ) GO TO 400
IF( TEST(9) ) 305,315,305
305 NCARDS = (TEST(8)-TEST(7))/TEST(9) + 1.5
IF( NCARDS*(1001-NCARDS) ) 2100,2100,320
310 CONTINUE

C
C THE UNITS CODE IS INCORRECT.
C FMT(1) = (+6HUNITS )
C GO TO 130

C
C PRINT THE DATA.
315 TEST(8) = TEST(7)
NCARDS = 1
320 IF( LINES.LT.LINMAX-5 ) GO TO 330
PRINT 322
322 FORMAT( 1H1 )
LINES = 1
GO TO 340
330 IF( IHEAD.EQ.1 ) GO TO 350
PRINT 332
332 FORMAT( // )
LINES = LINES + 3
340 PRINT 342
342 FORMAT( 25X 73HGROUP COORDINATE UNITS INITIAL
1 FINAL INCREMENT, / )

```

```

      LINES = LINES + 2
      IHEAD = 1
C
C  SET THE VARIABLE FORMAT.
350  FMT(1) = (+6H( 24X )
      FMT(2) = (+6H6A6, 3)
      IF( UNITS(1,IUNITS).GT.2.0E-3 ) GO TO 360
      FMT(3) = (+6HF12.2))
      GO TO 370
360  FMT(3) = (+6HF12.5))
370  PRINT FMT, (TEST(J),J=1,9)
      LINES = LINES + 1
      TEST(7) = TEST(7) * UNITS(1,IUNITS)
      TEST(8) = TEST(8) * UNITS(1,IUNITS)
      TEST(9) = TEST(9) * UNITS(1,IUNITS)
      GO TO (380,2000,3000,4000,5000,6000,380,380,380,9100,100), IGROUP
C
C  THE CODES ARE INCONSISTENT.
380  PRINT 382
382  FORMAT( 10X 33HTHE ABOVE CODES ARE INCONSISTENT. )
      GO TO 150
C
C  CHECK THE AXES CARD.
C  -----
400  IF( NTAPE1.EQ.0 ) NTAPE1=1
      IF( IUNITS.GT.4 ) GO TO 420
      IPAPER = 600 - 500 * ((IUNITS-1)/2)
      DO 410 J=1,3
      IF( TEST(J+6) * (100.0*UNITS(1,3)-TEST(J+6)*UNITS(1,IUNITS)) )
1  420,410,410
410  CONTINUE
      GO TO (420,420,420,4100,5100,6100,7100,420,420), IGROUP
C
C  THE AXES CARD IS INCORRECT.
420  PRINT 422
422  FORMAT( 10X 37HTHE FOLLOWING AXES CARD IS INCORRECT. )
      GO TO 140
C
C  READ THE LOSS TABLE.
C  -----
500  IHEAD = 0
      LINES = LINES + 28
      IF( LINES.LT.LINMAX-5 ) GO TO 510
      PRINT 322
      LINES = 25
      GO TO 520
510  PRINT 332
520  IF( IGROUP.EQ.4 ) GO TO 540
      IF( IGROUP.NE.5 ) GO TO 120
      IF( ICOORD.EQ.4 ) GO TO 530
      TEST(12) = BPHASE(FREQ)
      GO TO 100
530  FREQ = TARGET(1008,3) / UNITS(1,28)
      LINES = LINES + 5
      IF ( TEST(9) .LE. 0.0 ) TEST (9) = 500.0
      TEST(12) = BLOSS( FREQ,TEST(5),TEST(7),TEST(8),TEST(9) )

```



```

GO TO 100
540 IF( ICOORD.EQ.4 ) GO TO 550
TEST(12) = SPHASE(FREQ)
GO TO 100
550 TEST(12) = SLOSS(FREQ)
GO TO 100

```

```

C
C
C CHECK THE NUMBER OF CARDS IN THE PROFILE.
C -----

```

```

600 NCARDS = TEST(7)
IF( (NCARDS.GE.2).AND.(200.GE.NCARDS) ) GO TO 610
PRINT 602, (TEST(J),J=1,4), NCARDS
602 FORMAT( 10X 27H THE NUMBER OF CARDS IN THE , 2(A6,A4),
1 110, 44H, EXCEEDS 200 CARDS OR IS LESS THAN 2 CARDS. )
GO TO 150

```

```

C
C PRINT THE HEADING.
610 IHEAD = 0
LINES = NCARDS/2 + 10 + LINES
IF( LINES.LT.LINMAX-1 ) GO TO 620
PRINT 322
LINES = NCARDS/2 + 6
GO TO 630
620 PRINT 332
630 PRINT 632, (TEST(J),J=1,4)
632 FORMAT( 51X 2(A6,A4), /, 51X 17H-----, / )

```

```

C
C
C CHECK THE UNITS CODE.
C -----

```

```

700 READ 101, TEST(1),TEST(10),TEST(2),TEST(11),TEST(3),TEST(12)
J = 1
710 DO 730 I=1,32
IF( TEST(J).GT.UNITS(2,I) .OR. TEST(J).LT.UNITS(2,I) ) GO TO 730
IF( J.GT.1 ) GO TO 720
IUNITS = I
J = 2
GO TO 710
720 IF( J.GT. 2 ) GO TO 725
JUNITS = I
J = 3
IF( IGROUP.EQ. 7 ) GO TO 710
GO TO 740
725 KUNITS = I
GO TO 740
730 CONTINUE

```

```

C
C THE UNITS CODE IS INCORRECT.
C FMT(1) = (+6HUNITS )
PRINT 132, FMT(1)
PRINT 142, TEST(1),TEST(3),TEST(2),TEST(4)
GO TO 150

```

```

C
C SET THE VARIABLE FORMAT.
740 FMT(1) = (+6H( 2( )
FMT(2) = (+6H I15, )
IF( UNITS(1,IUNITS).GT.2.0E-3 ) GO TO 750

```

```

      FMT(3) = (+6HF14.2,)
      GO TO 760
750  FMT(3) = (+6HF14.5,)
760  IF (IGROUP .EQ. 7) GO TO 763
      LUNITS = JUNIT5
      GO TO 765
763  LUNITS = KUNIT5
765  IF ( UNITS(1,LUNITS) .GT. 2.0E-3 ) GO TO 770
      FMT(4) = (+6HF16.2,)
      GO TO 780
770  FMT(4) = (+6HF16.5,)
780  FMT(5) = (+6H15X) )
      GO TO (380,380,380,4200,5200,6200,7200,380,380), IGROUP

```

C  
C  
C  
C  
C

```

      READ AND WRITE A COMMENT CARD.
      -----
1000  READ 1001, (TEST(J),J=1,12)
1001  FORMAT( 12A6 )
1002  FORMAT( 10X 12A6 )
      IF( LINES.LT.LINMAX ) GO TO 1005
      PRINT 322
      LINES = 1
1005  PRINT 1002, (TEST(J),J=1,12)
      LINES = LINES + 1
      ICMNT = ICMNT + 1
      IF( ICMNT.GT.1 ) GO TO 100
      DO 1010 J=1,12
1010  CMMNT(J) = TEST(J)
      GO TO 100

```

C  
C  
C  
C  
C

```

      CONVERT AND STORE THE TARGET DATA.
      -----
2000  IF( ICOORD.GT.2 ) GO TO 380
      IF( NTAPE2.EQ.0 ) NTAPE2=1
      TARGET(1004,ICOORD) = UNITS(1,IUNITS)
      TARGET(1005,ICOORD) = UNITS(2,IUNITS)
      N = TARGET(1010,ICOORD)
      NCARDS = N + NCARDS
      IF( NCARDS.GT.1000 ) GO TO 2100
      TARGET(1010,ICOORD) = NCARDS
      N = N + 1
      DO 2010 I=N,NCARDS
2010  TARGET(I,ICOORD) = TEST(7) + (I-N)*TEST(9)
      GO TO 100

```

C  
C

```

      THE NUMBER OF ENTRIES HAS BEEN EXCEEDED.
2100  PRINT 2102, GROUP(IGROUP), COORD(ICOORD)
2102  FORMAT( 10X 14HTHE NUMBER OF , A6, 1XA5,
1 23HS EXCEEDS 1000 ENTRIES. )
      GO TO 150

```

C  
C  
C  
C

```

      CONVERT AND STORE THE SONAR DATA.

```

```

C -----
3000 IF( ICOORD-3 ) 3100,3200,380
3100 SONAR(1,ICOORD) = TEST(7)
      SONAR(2,ICOORD) = TEST(8)
      SONAR(3,ICOORD) = TEST(9)
      SONAR(4,ICOORD) = UNITS(1,IUNITS)
      SONAR(5,ICOORD) = UNITS(2,IUNITS)
      GO TO 100

C
C STORE THE SONAR ANGLE DATA.
3200 IF( ABS(TEST(7)).GT.1.5707 .OR. TEST(8).GT.1.5707 ) GO TO 3300
      ANGLES(1004) = UNITS(1,IUNITS)
      ANGLES(1005) = UNITS(2,IUNITS)
      N = ANGLES(1010)
      NCARDS = N + NCARDS
      IF( NCARDS.GT.1000 ) GO TO 2100
      ANGLES(1010) = NCARDS
      N = N + 1
      DO 3210 I=N,NCARDS
3210  ANGLES(I) = TEST(7) + (I-N)*TEST(9)
      GO TO 100

C
C THE SONAR ANGLES EXCEED THEIR BOUNDS.
3300 PRINT 3302
3302  FORMAT(10X50HALL SONAR ANGLES MUST LIE BETWEEN -90 AND +90 DEG.)
      GO TO 150

C
C
C
C CONVERT AND STORE THE SURFACE DATA.
C -----
4000 IF( ICOORD,NE,2 ) GO TO 380
      SURFAC(1) = TEST(7)
      SURFAC(2) = TEST(8)
      SURFAC(3) = TEST(9)
      SURFAC(4) = UNITS(1,IUNITS)
      SURFAC(5) = UNITS(2,IUNITS)
      GO TO 100

C
C STORE THE SURFACE AXES DATA.
4100 SP(207,1) = 2.777777777E-4/UNITS(1,IUNITS)
      SP(207,2) = SP(207,1)
      SP(208,1) = TEST(7)
      SP(208,2) = TEST(8)
      GO TO 5100

C
C
C READ AND PRINT THE SURFACE PROFILE.
C -----
4200 SP(204,1) = UNITS(1,IUNITS)
      SP(205,1) = UNITS(2,IUNITS)
      SP(204,2) = UNITS(1,IUNITS)
      SP(205,2) = UNITS(2,IUNITS)
      SP(210,1) = NCARDS
      SP(210,2) = TEST(5)
      SURFAC(4) = 0.0
      PRINT 4202, SP(205,1),SP(205,2),SP(205,1),SP(205,2)
4202  FORMAT( 2(12X 16HCARD RANGE=, A6, 9H DEPTH=, A6, 11X), / )

```

```

      READ 4212, (SP(N,1),SP(N,2),N=1,NCARDS)
4212  FORMAT( 2F10.5 )
      J = ( NCARDS + 1 ) / 2
      DO 4220 L=1,J
      N = L + J
      IF( N.LE,NCARDS ) GO TO 4220
      PRINT FMT, L,SP(L,1),SP(L,2)
      GO TO 4230
4220  PRINT FMT, L,SP(L,1),SP(L,2), N,SP(N,1),SP(N,2)
C
C      CONVERT AND CHECK THE PROFILE.
4230  DO 4260 N=1,NCARDS
      SP(N,1) = SP(N,1) * SP(204,1)
      SP(N,2) = SP(N,2) * SP(204,2)
C
C      IS THE RANGE INCREASING.
      IF( N.EQ,1 ) GO TO 4260
      IF( SP(N,1).GT,SP(N-1,1) ) GO TO 4260
      NCARDS = N
      GO TO 4270
4260  CONTINUE
      GO TO 100
C
C      A CARD IS INCORRECT OR OUT OF ORDER.
4270  PRINT 4272, NCARDS
4272  FORMAT( 10X 11HCARD NUMBER, I4, 13HIS INCORRECT. )
      GO TO 150
C
C
C
C      CONVERT AND STORE THE BOTTOM DATA.
-----
5000  IF( ICOORD,NE,2 ) GO TO 380
      BOTTOM(1) = TEST(7)
      BOTTOM(2) = TEST(8)
      BOTTOM(3) = TEST(9)
      BOTTOM(4) = UNITS(1,IUNITS)
      BOTTOM(5) = UNITS(2,IUNITS)
      GO TO 100
C
C      STORE THE BOTTOM AXES DATA.
5100  BP(207,1) = 2.77777777E-4/UNITS(1,IUNITS)
      BP(207,2) = BP(207,1)
      BP(208,1) = TEST(7)
      BP(208,2) = TEST(8)
      GO TO 100
C
C
C
C      READ AND PRINT THE BOTTOM PROFILE.
-----
5200  BP(204,1) = UNITS(1,IUNITS)
      BP(205,1) = UNITS(2,IUNITS)
      BP(204,2) = UNITS(1,JUNITS)
      BP(205,2) = UNITS(2,JUNITS)
      BP(210,1) = NCARDS
      BP(210,2) = TEST(5)
      BOTTOM(4) = 0.0
      PRINT 4202, BP(205,1),BP(205,2),BP(205,1),BP(205,2)

```



```

READ 4212, (BP(N,1),BP(N,2),N=1,NCARDS)
J = ( NCARDS + 1 ) / 2
DO 5220 L=1,J
N = L + J
IF( N,LE,NCARDS ) GO TO 5220
PRINT FMT, L,BP(L,1),BP(L,2)
GO TO 5230
5220 PRINT FMT, L,BP(L,1),BP(L,2), N,BP(N,1),BP(N,2)
C
C CONVERT AND CHECK THE PROFILE.
5230 DO 5260 N=1,NCARDS
BP(N,1) = BP(N,1) * BP(204,1)
BP(N,2) = BP(N,2) * BP(204,2)
C
C IS THE RANGE INCREASING.
IF( N,EQ,1 ) GO TO 5260
IF( BP(N,1).GT,BP(N-1,1) ) GO TO 5260
NCARDS = N
GO TO 4270
5260 CONTINUE
GO TO 100
C
C
C
C
C CONVERT AND STORE THE VELOCITY DATA.
-----
6000 IF( ICOORD,NE,5 ) GO TO 380
TOLERA(1) = TEST(7)
TOLERA(2) = TEST(8)
TOLERA(3) = TEST(9)
TOLERA(4) = UNITS(1,IUNITS)
TOLERA(5) = UNITS(2,IUNITS)
GO TO 100
C
C STORE THE VELOCITY AXES DATA.
6100 VP(207,1) = 2.777777777E-4/UNITS(1,IUNITS)
VP(207,2) = VP(207,1)
VP(208,1) = TEST(7)
VP(208,2) = TEST(8)
GO TO 100
C
C
C
C READ AND PRINT THE VELOCITY PROFILE.
-----
6200 VP(204,1) = UNITS(1,IUNITS)
VP(205,1) = UNITS(2,IUNITS)
VP(204,2) = UNITS(1,JUNITS)
VP(205,2) = UNITS(2,JUNITS)
VP(210,1) = NCARDS
VP(210,2) = TEST(5)
PRINT 6202, VP(205,1),VP(205,2),VP(205,1),VP(205,2)
6202 FORMAT(2(12X 16HCARD DEPTH-, A6, 10H VELOCITY-, A6, 10X), /)
READ 4212, (VP(N,1),VP(N,2),N=1,NCARDS)
6210 J = ( NCARDS + 1 ) / 2
DO 6220 L=1,J
N = L + J
IF( N,LE,NCARDS ) GO TO 6220
PRINT FMT, L,VP(L,1),VP(L,2)

```

```
GO TO 6230
6220 PRINT FMT, L,VP(L,1),VP(L,2), N,VP(N,1),VP(N,2)
C
C      CONVERT AND CHECK THE PROFILE.
6230 DO 6260 N=1,NCARDS
    VP(N,1) = VP(N,1) * VP(204,1)
    VP(N,2) = VP(N,2) * VP(204,2)
    IF( VP(N,2).GT.1.55 .AND. 1.77.GT.VP(N,2) ) GO TO 6240
C
C      THE VELOCITY EXCEEDS ITS BOUNDS.
PRINT 6232, N
6232 FORMAT( 10X 28HVELOCITY PROFILE CARD NUMBER, I4,
1     20M EXCEEDS ITS BOUNDS. )
GO TO 150
C
C      IS THE DEPTH INCREASING.
6240 IF( N.EQ.1 ) GO TO 6260
IF( VP(N,1).GT.VP(N-1,1) ) GO TO 6260
NCARDS = N
GO TO 4270
6260 CONTINUE
GO TO 100
C
C
C      CONVERT AND STORE TEMPERATURE DATA.
-----
C
C      STORE THE THERMAL AXES DATA.
7100 TP(207,1) = 2.7777777E-4/UNITS(1,IUNITS)
TP(207,2) = TP(207,1)
TP(207,3) = TP(207,1)
TP(208,1) = TEST (7)
TP(208,2) = TEST (8)
TP(208,3) = TEST (9)
GO TO 100
C
C
C      READ AND PRINT THE THERMAL PROFILE.
-----
C
7200 VP(204,1) = UNITS(1,IUNITS)
VP(205,1) = UNITS(2,IUNITS)
VP(204,2) = UNITS(1,KUNITS)
VP(205,2) = UNITS(2,KUNITS)
VP(210,1) = NCARDS
VP(210,2) = TEST(5)
TP(204,1) = UNITS(1,IUNITS)
TP(205,1) = UNITS(2,IUNITS)
TP(204,2) = UNITS(1,JUNITS)
TP(205,2) = UNITS(2,JUNITS)
TP(204,3) = UNITS(1,9)
TP(205,3) = UNITS(1,10)
TP(210,1) = NCARDS
TP(210,2) = TEST(8)
TP(210,3) = TEST (9)
PRINT 7202, TP(205,1),TP(205,2),TP(205,1),TP(205,2)
7202 FORMAT(2(6X,16HCARD          DEPTH-,A6,12HTEMPERATURE-,A6,14HSALINITY
```

```

1-/1000,6X),/)
READ 7205, (TP(N,1),TP(N,2),TP(N,3),N=1,NCARDS)
7205 FORMAT(3F10.5)
C
C TEST WHICH SALINITY INPUT TO USE.
C
SAL = 0.0
DO 7207 I = 1,NCARDS
IF ( TP(I,3) ) 7208, ,
SAL = SAL + TP(I,3)
IF (SAL .GT. 0.0) GO TO 7215
7207 CONTINUE
GO TO 7210
7208 PRINT 7237, I
PRINT 7209
7209 FORMAT (10X,36HNEGATIVE SALINITY IS NOT VALID DATA.)
GO TO 150
7210 DO 7212 I = 1,NCARDS
TP(I,3) = TP(210,3)
7212 CONTINUE
C
C PRINT THE TEMPERATURE PROFILE.
C
7215 J = ( NCARDS + 1 )/2
DO 7220 L=1,J
N = L + J
IF (N .LE. NCARDS) GO TO 7220
PRINT 7225, L,TP(L,1),TP(L,2),TP(L,3)
GO TO 7226
7220 PRINT 7225, L,TP(L,1),TP(L,2),TP(L,3),N,TP(N,1),TP(N,2),TP(N,3)
7225 FORMAT(2(6X,I3,6X,F8.2,8X,F7.2,11X,F7.2,10X))
7226 PRINT 7227, TP(210,2)
7227 FORMAT(//,45X,12HLATITUDE = ,F10.5,8H DEGREES,/)
C
C CONVERT AND CHECK TEMPERATURE PROFILE
C
7230 DO 7260 N=1,NCARDS
IF (JUNITS .EQ. 31) GO TO 7235
TP(N,2) = (TP(N,2) - 32.) * TP(204,2)
7235 IF (TP(N,2) .GT. -3.0 .AND. 35.0 .GT. TP(N,2)) GO TO 7250
C
C THE TEMPERATURE EXCEEDS NEPTUNIAN BOUNDS.
C
PRINT 7237, N
7237 FORMAT(10X,31HTEMPERATURE PROFILE CARD NUMBER,I4,19H EXCEEDS ITS B
10UNDS.)
C
C CHECK IF SALINITY IS WITHIN NEPTUNIAN BOUNDS.
C
7250 IF (SAL .GT. 0.0) GO TO 7254
K = N
IF (K .GT. 1 ) GO TO 7260
IF (TP(210,3) .GE. 0.0 .AND. 43.0 .GT. TP(210,3)) GO TO 7260
GO TO 7256
7254 IF (TP(N,3) .GE. 0.0 .AND. 43.0 .GT. TP(210,3)) GO TO 7260
C
C THE SALINITY EXCEEDS NEPTUNIAN BOUNDS.

```



```

7255 PRINT 7257
      PRINT 7237, N
      GO TO 7260
7256 PRINT 7257
7257 FORMAT(10X,40HSALINITY IS NOT WITHIN NEPTUNIAN BOUNDS.)
7260 CONTINUE
      CALL BT(TP)
C
C      PRINT THE HEADING
C
      IHEAD = 0
      LINES = NCARDS/2 + 10 + LINES
      IF (LINES .LT. LINMAX - 1) GO TO 7320
      PRINT 322
      LINES = NCARDS/2 + 6
      GO TO 7330
7320 PRINT 332
7330 PRINT 7335
7335 FORMAT ( 51X,17HVELOCITY PROFILE ,/,51X,17H-----,/)
C
C      PRINT THE VELOCITY PROFILE.
C
      PRINT 6202, VP(205,1),VP(205,2),VP(205,1),VP(205,2)
      GO TO 6210
C
C
C
C      PROCESS CONGRATS.
C
C      -----
8000 IF( PRINT.LT.TEST(3) .OR. PRINT.GT.TEST(3) ) GO TO 8010
      NPRINT = 1
      GO TO 8020
8010 NPRINT = 0
8020 FLD(27,9,PROCES) = NPRINT + 8 * (NTAPE1 + 8*NTAPE2)
C
C      IS THERE AT LEAST ONE COMMENT CARD.
      IF( ICMNT.GT.0 ) GO TO 8100
      PRINT 1001, (CMMNT(J),J=1,12)
      LINES = LINES + 1
C
C      INITIALIZE THE PLOTTER TAPE.
8100 IF( NTAPE1.NE.1 ) GO TO 8200
      CALL PLOTS( DATA,2048,1 )
      CALL PLOT(0.0,0.0,0,IPAPER)
      CALL PLOT(5.0,0.0,-3)
      CALL SYMBOL(0.0,0.0,0.0,14,CMMNT(1),90.0,72)
      CALL PLOT(5.0,0.0,-3)
      NTAPE1 = 2
C
C      SORT THE TARGET COORDINATES.
8200 DO 8260 J=1,2
      N = TARGET(1010,J)
      IF( N.LT.2 ) GO TO 8260
      L = 1
8210 I = L + 1
8220 IF( TARGET(L,J)-TARGET(I,J) ) 8250,8230,8240
8230 TARGET(I,J) = TARGET(N,J)
      N = N - 1

```



```

      GO TO 8250
8240  TARGET(N+1,J) = TARGET(I,J)
      TARGET(I,J) = TARGET(L,J)
      TARGET(L,J) = TARGET(N+1,J)
8250  I = I + 1
      IF( I.LE.N ) GO TO 8220
      L = L + 1
      IF( L.LT.N ) GO TO 8210
      TARGET(1010,J) = N
8260  CONTINUE
      CALL BTPL0T(TP)
C
C      SET THE MAXIMUM REVERSAL INCREMENT.
      IF( REVMAX(2).GT.REVMAX(1) ) GO TO 8270
      REVMAX(3) = 0.0
      GO TO 8300
8270  N = TARGET(1010,1)
      REVMAX(3) = (TARGET(N,1)-TARGET(1,1))/(REVMAX(2)-REVMAX(1))
C
C      SORT THE SONAR ANGLES.
8300  N = ANGLES(1010)
      IF( N.LT.1 ) GO TO 8400
      DO 8305 L=1,N
      IF( ABS(ANGLES(L)).GT.1.0E-4 ) GO TO 8305
      ANGLES(L) = 0.0
8305  CONTINUE
      IF( N.LT.2 ) GO TO 8400
      L = 1
8310  I = L + 1
8320  IF( ANGLES(L)-ANGLES(I) ) 8350,8330,8340
8330  ANGLES(I) = ANGLES(N)
      N = N - 1
      GO TO 8350
8340  ANGLES(N+1) = ANGLES(I)
      ANGLES(I) = ANGLES(L)
      ANGLES(L) = ANGLES(N+1)
8350  I = I + 1
      IF( I.LE.N ) GO TO 8320
      L = L + 1
      IF( L.LT.N ) GO TO 8310
      ANGLES(1010) = N
8400  RETURN
C
C
C      TERMINATE CONGRATS.
C      -----
9000  PRINT 9002
9002  FORMAT( 1H1, 9X 28HCONGRATS HAS BEEN COMPLETED. , /, 1H1 )
9030  IF( NTAPE2.EQ.0 ) GO TO 9090
      END FILE 2
9090  STOP 5
C
C
C      READ MISCELLANEOUS DATA.
C      -----

```

```
C      READ THE FREQUENCY.
9100  TARGET(1008,3) = TEST(7)
      IF( (IUNITS-27)*(IUNITS-28) ) 380,9110,380
9110  TARGET(1008,1) = ATTN(TARGET(1008,3))
      PRINT 9112, TARGET(1008,1)
9112  FORMAT( 24X, 12HATTENUATION , 12X 6HDB/KYD, 6X F12.5 )
      LINES = LINES + 1
      GO TO 100

C
C      READ THE MAXIMUM NUMBER OF REVERSALS.
9200  REVMAX(1) = TEST(7)
      REVMAX(2) = MAX(TEST(7),TEST(8))
      REVMAX(4) = TEST(9)
      TEST(8) = REVMAX(2)
      IUNITS = 15
      IF( REVMAX(2).LT.201.0 ) GO TO 320
      PRINT 9202
9202  FORMAT( 10X45HTHE MAXIMUM NUMBER OF REVERSALS EXCEEDS 200.0 )
      GO TO 140
      END
```

C  
C  
C  
C  
C  
C  
C

FUNCTION BLOSS AND SLOSS FOR CONGRATS. CHIC WEINBERG

-----  
READ AND PRINT THE LOSS TABLE.  
-----

```

FUNCTION BLOSS( FREQ,TEST,POR,DBMIN,DBMAX )
DOUBLE PRECISION R,Z,RB,ZB,COS2B,RAD2B,SIN2B
DIMENSION DB(92,4)/276*0.0,92*3.14159265/
DIMENSION TYPE(10)/60H      AMOS MGS1 MGS2 MGS3 MGS4 MGS5
1NEL NUWC OTHERS
PRINT 2
2  FORMAT( 54X 11HBOTTOM LOSS, /, 54X 11H-----, / )
   J = 1
   DO 10 I=1,10
   IF( TEST.GT.TYPE(I) .OR. TEST.LT.TYPE(I) ) GO TO 10
   ITYPE = I - 1
   IF( -ITYPE .LE. 0 ) GO TO 100
   CALL BTMLOS( FREQ,DB,ITYPE,POR,DBMIN,DBMAX,$110 )
10  CONTINUE

C  ENTRY SLOSS( FREQ )
   PRINT 12
12  FORMAT( 54X 12HSURFACE LOSS, /, 54X 12H-----, / )
   J = 2
   GO TO 100

C  ENTRY BPHASE(FREQ)
   PRINT 22
22  FORMAT( 54X 12HBOTTOM PHASE, /, 54X 12H-----, / )
   J = 3
   GO TO 100

C  ENTRY SPHASE(FREQ)
   PRINT 32
32  FORMAT( 54X 13HSURFAC PHASE, /, 54X 13H-----, / )
   J = 4
100 READ 101, (DB(I,J),I=1,91)
101  FORMAT( 10F5.1 )
110  DB(92,J) = DB(91,J)
   IF( J.GT.2 ) GO TO 150
   PRINT 112
112  FORMAT( 5(24H      ANGLE      LOSS      ),
1    /, 5(24H      DEG      DB      ), / )
   GO TO 160
150  PRINT 152
152  FORMAT( 5(24H      ANGLE      PHASE      ),
1    /, 5(24H      DEG      DEG      ), / )
160  DO 170 I=1,18
   I1 = I - 1
   I2 = I1 + 19
   I3 = I2 + 18
   I4 = I3 + 18
   I5 = I4 + 18
170  PRINT 172, I1,DB(I1+1,J), I2,DB(I2+1,J), I3,DB(I3+1,J),
1    I4,DB(I4+1,J), I5,DB(I5+1,J)

```

```

172 FORMAT( I8,F11.2, I13,F11.2, I13,F11.2, I13,F11.2, I13,F11.2 )
    I1 = 18
    PRINT 172, I1,DB(I1+1,J)
    IF ( ITYPE .GT. 0 ) PRINT 174, TYPE(ITYPE+1)
174 FORMAT(/,40X,'METHOD OF BOTTOM LOSS COMPUTATION: ',A6)
    IF ( POR .GT. 0.0 ) PRINT 175, POR
175 FORMAT ( 52X,'POROSITY = ',F4.2)
    IF (DBMIN .GT. 0.0 .OR. DBMIN .LT. 0.0 ) PRINT 176, DBMIN
176 FORMAT ( 41X,'MINIMUM LIMIT FOR BOTTOM LOSS = ',F6.2)
    IF ( DBMAX .GT. 0.0 .AND. DBMAX .LT. 500.0 ) PRINT 177, DBMAX
177 FORMAT ( 41X,'MAXIMUM LIMIT FOR BOTTOM LOSS = ',F6.2)
    FREQUE = FREQ
    IF( J,LE,2 ) GO TO 190

C
C   CONVERT THE PHASE TO RADIANS.
    DO 180 I=1,92
180 DB(I,J) = DB(I,J) * 1.74532925E-2
190 RETURN

C
C
C   USE THE LOSS TABLE.
    -----
    ENTRY BOTLOS(R,Z,RB,ZB,PHASE)
    J = 1
    GO TO 200

C
    ENTRY SURLOS(R,Z,RB,ZB,PHASE)
    J = 2
200 IF( R*RB+Z*ZB ) 220,210,220
210 ANGLE = 90.0
    GO TO 230
220 ANGLE = 57.29578D+0 * ATAN((R*ZB-Z*RB)/(R*RB+Z*ZB))
230 I = ABS(ANGLE) + 1.0
    ANGLEI = I - 1
    BLOSS = DB(I,J) + (DB(I+1,J)-DB(I,J)) * (ABS(ANGLE)-ANGLEI)
    PHASE = DB(I,J+2) + (DB(I+1,J+2)-DB(I,J+2)) * (ABS(ANGLE)-ANGLEI)

C
C
C   COMPUTE THE DIRECTION NUMBERS OF THE REFLECTED RAY.
    -----
    RAD2B = RB*RB + ZB*ZB
    COS2B = (RB+ZB)*(RB-ZB) / RAD2B
    SIN2B = 2.0D+0*RB*ZB/RAD2B
    RAD2B = COS2B*R + SIN2B*Z
    Z      = SIN2B*R - COS2B*Z
    R      = RAD2B
    RETURN
    END

```



SUBROUTINE BTMLOS (FREQ,DB,ITYPE,POR,DBMIN,DBMAX,S)

DIMENSION DB(91)  
DIMENSION FR(8)/0.1,0.3,0.5,1.0,1.5,2.5,4.0,6.5/  
DIMENSION FVAL(8)/0.157,0.45,0.67,1.0,1.18,1.43,1.7,2.0/  
GO TO (100,1000,2000,3000,4000,5000,6000,7000,9000),ITYPE

-----  
BOTTOM LOSS FROM AMOS DATA.  
-----

100 FREQUE = FREQ  
FRQLG2 = LOG(FREQUE)/LOG(2.0)

GRAZING ANGLES ARE 0 THROUGH 14.

F = FRQLG2  
FSQ = F\*F  
FCUBE = FSQ\*F  
F4PWR = FCUBE\*F  
DB(1) = 0.0  
DO 110 I = 1,14  
THETA = I  
TH = 0.2\*(THETA - 10.0)

110 DB(I+1) = 2.96026 + 1.26990\*F + 1.60430\*TH + 0.25257\*FSQ  
1 + 0.66161\*F\*TH + 0.06072\*TH\*TH + 0.02000\*FCUBE  
2 + 0.09833\*FSQ\*TH - 0.01888\*F\*TH\*TH - 0.02619\*TH\*\*3  
3 - 0.00303\*F4PWR + 0.00778\*FCUBE\*TH - 0.00833\*FSQ\*TH\*TH  
4 - 0.01250\*F\*TH\*\*3 - 0.01310\*TH\*\*4

TEST FOR FREQUENCY GREATER THAN 1.0 KC.

IF (FREQUE .GT. 1.0) GO TO 200

FREQUENCY IS NOT GREATER THAN 1.0 KC  
-----

F = 2.0\*FRQLG2 + 3.0  
FSQ = F\*F  
FCUBE = FSQ\*F  
F4PWR = FCUBE\*F

GRAZING ANGLES ARE 15 THROUGH 39

DO 120 I=15,39  
THETA = I  
TH = 0.2\*(THETA - 30.0)

120 DB(I+1) = 4.35024 + 1.17091\*F + 0.46874\*TH + 0.08272\*FSQ  
1 + 0.17115\*F\*TH - 0.07547\*TH\*TH - 0.00386\*FCUBE  
2 + 0.01295\*FSQ\*TH - 0.01678\*F\*TH\*TH - 0.00555\*TH\*\*3  
3 - 0.00003\*F4PWR - 0.00193\*FCUBE\*TH - 0.00074\*FSQ\*TH\*TH  
4 - 0.00224\*F\*TH\*\*3

GRAZING ANGLES ARE 40 THROUGH 60

DO 130 I=40,60  
THETA = I

```

130  TH = 0.2*(THETA - 50.0)
      DB(I+1) = 4.84820 + 1.46858*F - 0.11457*TH + 0.11036*FSQ
1      - 0.01238*F*TH - 0.00953*TH*TH - 0.01000*FCUBE
2      - 0.00375*FSQ*TH - 0.00929*F*TH*TH + 0.00833*TH**3
3      - 0.00042*FCUBE*TH - 0.00268*FSQ*TH*TH + .00830*F*TH**3
4      - 0.00208*TH**4

```

GRAZING ANGLES ARE 61 THROUGH 90

**F = FRQLG2**

DO 140 I=61,90

```
140 DB(I+1) = DB(I) - 0.085667 - 0.025434*F
GO TO 9000
```

**GO TO 9000**

FREQUENCY IS GREATER THAN 1.0 KC.

200 F = FRQLG2 - 1  
FSQ = F \* F  
FCUBE = FSQ \* F  
F4PWR = FCUBE \* F

$$F4PWR = FCUBE * F$$

GRAZING ANGLES ARE 15 THROUGH 39

DO 220 I=15,39

THETA = 1

$$TH = 0.2 * (THETA - 30.0)$$

```

220  OB(I+1) = 12.25083 + 3.88808*F + 1.14802*TH + 0.16312*FSQ
      1      + 0.04386*F*TH - 0.18835*TH*TH - 0.02857*FCUBE
      2      - 0.08214*FSQ*TH - 0.05952*F*TH*TH + 0.00667*TH**3
      3      + 0.01071*F4PWR - 0.00179*FCUBE*TH + 0.00476*FSQ*TH*TH
      4      + 0.01389*F*TH**3 - 0.00348*TH**4

```

$$+ 0.01389 * F * TH^{**3} - 0.00348 * TH^{**4}$$

GRAZING ANGLES ARE 40 THROUGH 60

DO 230 I=40,60

THETA = 1

$$TH = 0.2 * (THETA - 50.0)$$

```

230 DB(I+1) = 13.59067 + 3.74190*F - 0.25928*TH + 0.13266*FSQ
      1 - 0.03764*F*TH - 0.06816*TH*TH - 0.01333*FCUBE
      2 + 0.01214*FSQ*TH - 0.00959*F*TH*TH + 0.00500*TH**3
      3 - 0.02000*F4PWR - 0.00167*FCUBE*TH + 0.00867*FSQ*TH*TH
      4 - 0.00167*F*TH**3 + 0.00083*TH**4

```

$$- 0.00167 * F * TH^{**3} + 0.00083 * TH^{**4}$$

GRAZING ANGLES ARE 61 THROUGH 90

**F = FRQLG2**

DO 240 I=61,90

```
240 DB(I+1) = DB(I) - 0.126002 - 0.000333*F + 0.034002/F
GO TO 9000
```

**GO TO 9000**

**BOTTOM LOSS FOR ACOUSTIC PROVINCES. MGS 1 - 5.**

**BOTTOM LOSS FOR ACOUSTIC PROVINCE MGS 1.**

```

C -----
C
1000 DO 1020 I=0,90
      TH = I
1020 DB(I+1) = 2.2435*LOG(0.1260*TH + 1.496)
      GO TO 9000
C
C BOTTOM LOSS FOR ACOUSTIC PROVINCE MGS 2.
C -----
C
2000 DO 2020 I=0,90
      TH = I
2020 DB(I+1) = 3.4315*LOG(0.1056*TH + 2.842)
      GO TO 9000
C
C BOTTOM LOSS FOR ACOUSTIC PROVINCE MGS 3.
C -----
C
3000 DO 3020 I=0,90
      TH = I
3020 DB(I+1) = 2.4910*LOG(0.8864*TH + 10.526)
      GO TO 9000
C
C BOTTOM LOSS FOR ACOUSTIC PROVINCE MGS 4.
C -----
C
4000 DO 4020 I=0,90
      TH = I
4020 DB(I+1) = 2.8377*LOG(1.8754*TH + 15.685)
      GO TO 9000
C
C BOTTOM LOSS FOR ACOUSTIC PROVINCE MGS 5.
C -----
C
5000 DO 5020 I=0,90
      TH = I
5020 DB(I+1) = 2.4036*LOG(20.5760*TH + 82.440)
      GO TO 9000
C
C -----
C
C NAVAL ELECTRONIC LABORATORY EQUATIONS.
C LOSS DEPENDENT ON POROSITY OF BOTTOM.
C -----
C
6000 FREQUE = FREQ
      F = 10.0*LOG10(FREQUE)
      POROS = POR
      DO 6020 I=0,90
        TH = I
6020 DB(I+1) = (6.0 + 22.0*(POROS - 0.27) + F) * (TANH((POROS/0.24) *
1          (TH/57.295779)) + (1.0 - POROS/0.24)/12.5 *
2          TH*TH/8100.0)
      GO TO 9000
C
C -----

```

```

C   NAVAL UNDERSEA WARFARE CENTER EQUATIONS.
C   LOSS DEPENDENT ON POROSITY OF BOTTOM.
C   -----
C
7000  FREQUE = FREQ
      IF ( FREQUE - 0.1 ) 7030, 7030,
      IF ( FREQUE - 6.5 )      ,      , 7040
      DO 7020 I=1,8
      IF ( (FREQUE - FR(I))*(FR(I+1) - FREQUE) ) 7020,
      FUNU = FVAL(I) + (FREQUE - FR(I))*(FVAL(I+1) - FVAL(I))/(FR(I+1)
1      - FR(I) )
      GO TO 7100
7020  CONTINUE
7030  FUNU = FVAL(1)
      GO TO 7100
7040  FUNU = FVAL(8)
      GO TO 7100
7100  POROS = POR
      FRQFUN = (3.7 + 17.5*(POROS - 0.27) ) * FUNU
      PORTAN = POROS/13.75104
      SUPER = 1.5/POROS
      PORDIV = (1 - POROS/0.27)/101250.0
      DO 7120 I=0,90
      TH = I
7120  DB(I+1) = FRQFUN*(TANH( (PORTAN*TH)**SUPER ) + PORDIV*TH*TH )
      GO TO 9000
C   -----
C   CHECK LOSS AGAINST MINIMUM AND MAXIMUM
C   -----
C
9000  DO 9010 I=1,91
      IF ( DB(I) .LT. DBMIN ) DB(I) = DBMIN
      IF ( DB(I) .GT. DBMAX ) DB(I) = DBMAX
9010  CONTINUE
9900  RETURN 7
      END

```